Aims :

- 1. Effects of flows on the magnetic field in high conductive plasma
- 2. Anti-dynamo theorem
- 3. Dynamo scenarios
	- *¡* Solar type dynamo
	- α^2 dynamo
	- *¡* cross-helicity dynamo?

Action of the plasma flow on the magnetic flux $2/25$

Magnetic flux is frozen in plasma flow if diffusion term is neglected. Let $\Phi = \int {\bf B}\cdot {\rm d}{\bf S}.$ The change of the flux is due to change of the induction $\frac{\partial \mathbf{B}}{\partial t}$ and due to the moving boundary δt **u** \times dl \cdot **B** = $-\delta t$ **u** \times **B** \cdot dl. Thus the flux rate change is

$$
\frac{\mathrm{d}\Phi}{\mathrm{d}t} = \int \frac{\partial \mathbf{B}}{\partial t} \cdot \mathrm{d}\mathbf{S} - \oint_C \mathbf{u} \times \mathbf{B} \cdot \mathrm{d}\mathbf{l} = 0
$$

or

$$
\frac{\mathrm{d}\Phi}{\mathrm{d}t} = \int \left(\frac{\partial \mathbf{B}}{\partial t} - \nabla \times (\mathbf{u} \times \mathbf{B}) \right) \cdot \mathrm{d}\mathbf{S} = 0
$$

Using vector calculus identity the induction equation can be rewritten as follows:

stretching compression advection diffusion ∂ **B** (**p** ∇)**, p**(∇ **,**) $\frac{\partial \mathbf{B}}{\partial t}$ = $(\mathbf{B} \cdot \nabla) \mathbf{u}$ $-\mathbf{B}(\nabla \cdot \mathbf{u})$ $-(\mathbf{u} \cdot \nabla) \mathbf{B} + \eta \Delta \mathbf{B}$

Fig. 3.5 Concentration of flux into ropes by a convective layer $(R_m = 10^3)$; (a) streamlines ψ = cst. where ψ is given by (3.85); (b) lines of force of the resulting steady magnetic field. (From Weiss, 1966.)

Compression and advection, SDO/HMI, 17/10/2016 4/25

Stretching 5/25

Consider the cylindrical coordinate system: r, ϕ, z , axisymmetric rotational flow: $(0,r\Omega(r,z),0)$, then the toroidal field is winding from poloidal by DR:

$$
\frac{\partial B_{\phi}}{\partial t} = r(\mathbf{B}_{p} \cdot \nabla)\Omega, \qquad (1)
$$
\n
$$
\frac{\partial \mathbf{B}_{p}}{\partial t} = 0
$$
\n
$$
\mathbf{B}_{p} = e_{r}B_{r} + e_{z}B_{z}
$$

The steady state is known as the *Ferraro* law: $(\mathbf{B}_p \cdot \nabla) \Omega$. The production of the net flux of the toroidal field in Eq.(12): $\frac{\text{d}}{\text{d}t} \int B_{\phi} \text{d}S_m = 0!$

Large-scale unipolar field stretched by DR, courtesy SSO 6/25

Anti-dynamo theorem and the state of the

Suppose that we allow for both poloidal and azimuthal velocity and magnetic fields, which may be steady or unsteady, but which are axisymmetric:

$$
\boldsymbol{B} = \boldsymbol{B^p} + \boldsymbol{B^{\phi}}, \boldsymbol{U} = \boldsymbol{U^p} + \boldsymbol{U^{\phi}}
$$

Then the induction equation can be divided fo the poloidal and toroidal parts:

$$
\partial_t \mathbf{B}^{\phi} = \nabla \times (\mathbf{U}^{\phi} \times \mathbf{B}^{\mathbf{p}} + \mathbf{U}^{\mathbf{p}} \times \mathbf{B}^{\phi}) + \eta \Delta \mathbf{B}^{\phi}, \partial_t \mathbf{B}^{\mathbf{p}} = \nabla \times (\mathbf{U}^{\mathbf{p}} \times \mathbf{B}^{\mathbf{p}}) - \nabla \times \eta \nabla \times \mathbf{B}^{\mathbf{p}}
$$

Using cylindrical coordinates and $\bm{B^p} \!=\! \bm{\nabla} \times r^{-1} A e^{\bm{\varphi}}$, and $\bm{U^{\varphi}} \!=\! e^{\bm{\varphi}} r \Omega$: :

$$
\frac{\mathrm{d} \mathbf{B}^{\phi}}{\mathrm{d} t} = r(\mathbf{B}^{p} \cdot \nabla)\Omega + \eta \nabla^{2} \mathbf{B}^{\varphi},
$$
\n
$$
\frac{\mathrm{d} A}{\mathrm{d} t} = \eta \nabla_{*}^{2} A, \nabla_{*}^{2} = \frac{\partial^{2}}{\partial z^{2}} + r \frac{\partial}{\partial r} \frac{1}{r} \frac{\partial}{\partial r}
$$

Note that

$$
\int_V A \frac{\mathrm{d}A}{\mathrm{d}t} \mathrm{d}V = \int_V A \eta \nabla_*^2 A \mathrm{d}V = -\eta \int_V (\nabla A)^2 \mathrm{d}V < 0,
$$

Anti-dynamo theorem and the state of the state

Therefore, A decays with time and B^{φ} will decay eventually as well:

$$
\frac{\mathrm{d} \boldsymbol{B}^{\phi}}{\mathrm{d} \mathrm{t}} = r(\boldsymbol{B}^{p} \cdot \boldsymbol{\nabla}) \mathrm{sin} \theta \Omega + \eta \nabla^{2} \boldsymbol{B}^{\varphi}
$$

Cowling's neutral point argument.

Suppose that we seek a steady, axisym metric dynamo in which \bm{B}^p is poloidal, $\bm{\mathsf{J}}$ is azimuthal, and $\bm{U^p}$ is also poloidal, $\partial_t \bm{B}^p$ $=$ $\qquad \qquad \blacklozenge \bm{\mathsf{B}}$ 0, in vicinity C_{ϵ} it should be:

$$
\int (U^p \times B^p) \mathrm{d}S_{\varepsilon} = \eta \oint_{C\varepsilon} B^p \mathrm{d}r
$$

The right part scales as $\varepsilon \eta |B_{\varepsilon}^p|$, and the left $\left\{\begin{array}{c} \sqrt{N}\end{array}\right\}$ $\mathsf{part}\ \mathsf{scales}\ \mathsf{as}\ \varepsilon^2 |U^p_\varepsilon||B^p_\varepsilon|,$ decrease faster. so, $\left\{\ \right.$

$$
\int (U^p \times B^p){\rm d} \mathrm{S} < \eta \oint B^p {\rm d} r
$$

Induction effect of *U ^p - B^p* doesnot compensate diffusion.

Dynamo scenarios en el proponero el proponero el proponero el proponero el proponero el proponero el proponero

Stretch-twist fold dynamo Zeldovich 1966

- Magnetic field is frozen-in a high conductive turbulent fluid.
- Breaking reflection symmetry of turbulent motions.
	- $-$ This can result in spontaneous self-induction of magnetic field

Reconnection and diffusion are important part of dynamo instability

Solar case 10/25

Linear stage **Nonlinear** stage

Solar dynamo scenarios 11/25

Observational restrictions on the solar dynamo scenarios 12/25

- $\bar{p} = -|B^p| \ll |B^t|$, where strength of the polar magnetic field during solar minims quantifies B^p and B^t is estimated by the magnetic field of the bipolar active regions
- Dynamo period and surface time-latitude diagrams
- $-$ Phase relations between polar and equatorial B^p and B^t also in space distributions, for example , $B_r B_\varphi < 0$ in the normal BMR for the magnetic activity maximum
- *¡* Extended 20 yr mode in Br (Stenflo 1994) and in the torsional oscillations (Ulrich 1998)
- Axisymmetric spherical harmonics spectrum (and phase of spherical harmonics)

General properties of the dynamo solution

Short waves approximation 15/25

Let us consider the isotropic α effect and turbulent diffusion, and the shear is unidorm:

$$
\partial_t \langle \mathbf{B} \rangle = \nabla \times (\mathcal{E} + \langle \mathbf{U} \rangle \times \langle \mathbf{B} \rangle),
$$

$$
\mathcal{E} = \langle \mathbf{u} \times \mathbf{b} \rangle = \alpha \langle \mathbf{B} \rangle - \eta_T \nabla \times \langle \mathbf{B} \rangle,
$$

$$
\langle \mathbf{B} \rangle = e^{\varphi} B + \nabla \times e^{\varphi} A, \langle \mathbf{U} \rangle = e^{\varphi} (\mathbf{r} \cdot \mathbf{S}), (e^{\varphi} \cdot \mathbf{S}) = 0
$$

After substitution:

$$
\frac{\partial e^{\varphi}B}{\partial t} = (B^p \cdot \nabla)(e^{\varphi}(\mathbf{r} \cdot \mathbf{S})) - \eta_T \nabla \times \nabla \times B e^{\varphi}
$$

$$
\frac{\partial e^{\varphi}A}{\partial t} = \alpha e^{\varphi}B - \eta_T \nabla \times \nabla \times A e^{\varphi}
$$

Use the eigen-wave representation: $B,A\!\sim\!\exp(\sigma t+{\rm i}\bm{k}\bm{\cdot}\bm{r})$ and $\bm{k}\bm{\cdot}\bm{e}^{\varphi}\!=\!0.$ Note, that

$$
\frac{\partial \boldsymbol e^{\varphi} A}{\partial t} \!\to\! \sigma \boldsymbol e^{\varphi} A; \nabla \times \boldsymbol e^{\varphi} A \!\to\! \text{i} \boldsymbol k \times \boldsymbol e^{\boldsymbol \varphi}; \nabla \times \nabla \times \boldsymbol A \, \boldsymbol e^{\varphi} \!\to\! -\eta_T \boldsymbol k^2 A \, \boldsymbol e^{\varphi};
$$

Therefore

$$
\sigma B = -i(\mathbf{k} \times \mathbf{S}) \cdot \mathbf{e}^{\varphi} A - \eta_T \mathbf{k}^2 B
$$

$$
\sigma A = \alpha B - \eta_T \mathbf{k}^2 A
$$

Then compatibility condition determine the eigen values:

$$
\begin{vmatrix}\n\sigma + \eta_T k^2 & i(\mathbf{k} \times \mathbf{S}) \cdot \mathbf{e}^{\varphi} \\
-\alpha & \sigma + \eta_T k^2\n\end{vmatrix} = 0
$$

The growing modes have $\text{Re}(\sigma) > 0$. The solution of the determinant is

$$
(\sigma + \eta_T k^2)^2 = -\mathrm{i}\alpha(\mathbf{k} \times \mathbf{S}) \cdot \mathbf{e}^{\varphi}
$$

There are two roots: depending on the sign of $\alpha(\boldsymbol{k}\times\boldsymbol{S})\cdot\boldsymbol{e}^{\varphi}$:

$$
\sigma = -\eta_T k^2 + \begin{cases} \frac{1+i}{\sqrt{2}} \sqrt{(\alpha(\mathbf{k} \times \mathbf{S}) \cdot e^{\varphi})}, & \text{if } \alpha(\mathbf{k} \times \mathbf{S}) \cdot e^{\varphi} > 0 \\ \frac{1-i}{\sqrt{2}} \sqrt{(-\alpha(\mathbf{k} \times \mathbf{S}) \cdot e^{\varphi})}, & \text{if } \alpha(\mathbf{k} \times \mathbf{S}) \cdot e^{\varphi} < 0 \end{cases}
$$

Suppose that $\sigma=\gamma-i\omega$, then, the dynamo frequency is $\omega=\pm\sqrt{\frac{1}{2}}|\alpha(\bm{k}\times\bm{S})\cdot\bm{e}^{\varphi}|$ and the $\sqrt{\frac{1}{2} |\alpha(\boldsymbol{k}\times\boldsymbol{S})\cdot\boldsymbol{e}^{\varphi}|}$ and the normalized increment is

$$
\hat{\gamma} = \frac{\gamma}{\eta_T k^2} = -1 + \sqrt{\text{D} \sin \psi},
$$

where, $D=\frac{\alpha D}{\alpha^2 L^3}$ is the dynamo number, αS is the dynamo number $\frac{\alpha}{\eta_T^2 k^3}$ is the dynamo number, and ψ is angle between \bm{k} and the shear vector $\bm{S}.$ Note, that, $S \sim \frac{S \wedge S \wedge S}{\partial r} \sim \Omega$, $\partial r\Omega$ $\frac{\partial \Gamma}{\partial r} \sim \Omega$, $\overline{}$

Wave propagation. Note, that *k* show propagation of phase of the dynamo wave. Therefore, the increment $\hat{\gamma}$ has maximum for $\psi = \pi/2$, i.e, the maximum of the dynamo efficiency is attained in direction which is perpendicular to the shear, in other words along the isorotation surface. This is the Parker-Yoshimura rule.

Wave frequency (Cycle period).

a)Linear growth. Consider the wavelength with maximum growth rate, i.e., consider wave with

$$
\text{extreme of }\gamma=-\eta_T k^2+\sqrt{\frac{\alpha k\Omega}{2}}\text{, (Brandenburg et al 2017)}
$$

$$
\frac{\partial \gamma}{\partial k} = -2\eta_T k + \frac{1}{2} \sqrt{\frac{\alpha \Omega}{k}} = 0
$$

$$
k_m = \sqrt[3]{\frac{\alpha \Omega}{16 \eta_T}}
$$

$$
\omega_{\rm cyc} = \left(\frac{\alpha \Omega}{2}\right)^{2/3} \left(\frac{1}{4\eta_T}\right)^{1/6}
$$

b) Saturation. The efficient dynamo number is close to the critical, $\omega_{\rm cyc} \sim \eta_T k^2$ - the cycle period is determine by the turbulent diffusion and it is independent of $\Omega.$

Dependence of cycle period on stellar rotation rate 16/25

Red and black crosses show the results of Brandenburg et al. (2017), green crosses those of Lehtinen et al. (2016) , orange squares the models of Warnecke (2018), and the asterisks are from the models of Pipin (2021);act/inact marks the active and inactive branches of
activity, respectively; while kin/nkin stand for
kinematic and non-kinematic models, respec-
tively. Note that $Co = 2\Omega\tau_c$, we employ $\alpha \sim 2^{\frac{5}{2}}$ activity, respectively; while kin/nkin stand for kinematic and non-kinematic models, respec tively. Note that $\text{Co} = 2\Omega \tau_c$, we employ $\alpha \sim$ $\frac{8}{9}$ $\Omega\tau_c$. So, for the rate:

$$
\frac{\omega_{\text{cyc}}}{\omega_{\text{rot}}} \sim \text{Co}^{1/3} \eta_T^{-1/6} \quad \text{active}
$$
\n
$$
\frac{\omega_{\text{cyc}}}{\omega_{\text{rot}}} \sim \text{Co}^{-1} \quad \text{saturated}
$$

The α^2 dynamo 17/25

Theoretical expectations about α^2 dynamo:

- 1) Steady. Evidence for the cyclic dynamo from DNS (Brandenburg et al 2015)
- 2) Toroidal and poloidal components have comparable magnitude (Raedler 1986)
- 3) Non-axisymmetric magnetic field grows faster than axisymmetric one

The α^2 dynamo 18/25

Here, we assume that α effect is isotropic, i.e. $\alpha_{\rm pp} = \alpha_{\varphi\varphi}$. After substitution:

$$
\frac{\partial e^{\varphi}B}{\partial t} = \nabla \times \alpha \nabla \times A e^{\varphi} - \eta_T \nabla \times \nabla \times B e^{\varphi}
$$
\n
$$
\frac{\partial e^{\varphi}A}{\partial t} = \alpha e^{\varphi}B - \eta_T \nabla \times \nabla \times A e^{\varphi}
$$

Use the eigen-wave representation: $B, A \sim \exp(\sigma t + i \mathbf{k} \cdot \mathbf{r})$. Proceeding in the similar way as previously we get

$$
\sigma B = \alpha k^2 A - \eta_T \mathbf{k}^2 B
$$

\n
$$
\sigma A = \alpha B - \eta_T \mathbf{k}^2 A
$$

Then compatibility condition determine the eigen values:

$$
\begin{vmatrix} \sigma + \eta_T k^2 & -\alpha k^2 \\ -\alpha & \sigma + \eta_T k^2 \end{vmatrix} = 0
$$

The growing modes have $\text{Re}(\sigma) > 0$. The solution of the determinant is

$$
\sigma = \alpha k - \eta_T k^2
$$

For the growing mode $\alpha > \eta_T k$, no wave, a stationary dynamo. The maximum generation rate wavelength is $k = \alpha / 2 \eta_T$.

Stellar activity magnitude, X-ray 19/2

For the partially convective stars we can expect $\alpha\Omega$ dynamo and for the fully convective- α^2 2

In the linear regime the growth rate for the $\alpha\Omega$ dynamo is

$$
\gamma_{\alpha\Omega}\,{\sim}\,\bigg(\frac{\alpha\Omega}{2}\bigg)^{\!2/3}\bigg(\frac{1}{4\eta_T}\bigg)^{\!1/6}\,{\sim}\,\Omega^{4/3}
$$

and for α^2 2

$$
\gamma_{\alpha 2} \sim \frac{\alpha^2}{2\eta_T} \sim \Omega^2
$$

Here we do not take into account $\eta_T(\Omega)$

Effect of rotation on the turbulence 20/25

The large Reynolds number limit. Consider the forced turbulence

$$
\frac{u}{\tau_c}\!\approx\!2u\times\Omega+\frac{u^{(0)}}{\tau_c}\!\cdots
$$

Let us divide the flow into sum along and perpendicular to the rotation axis:

$$
\boldsymbol{u} \!=\! \boldsymbol{u}_\perp \!+\boldsymbol{u}_\parallel, \boldsymbol{u}_\perp \!=\! \boldsymbol{u} -\frac{\boldsymbol{\Omega}}{\boldsymbol{\Omega}^2}(\boldsymbol{u}\cdot\boldsymbol{\Omega}); \boldsymbol{u}_\parallel \!=\! \frac{\boldsymbol{\Omega}}{\boldsymbol{\Omega}^2}(\boldsymbol{u}\cdot\boldsymbol{\Omega})
$$

Assume that in the background turbulence (without global rotation) is isotropic, $\langle u^{(0)2}_\perp \rangle = \langle u^{(0)2}_\perp \rangle$ $\rangle =$ $\langle u^{(0)2}_{\parallel} \rangle$. Then

$$
(\delta_{ij} - 2\tau_c \varepsilon_{ijn} \Omega_n) u_{\perp j} = u_{\perp i}^{(0)}; u_{\parallel i} = u_{\parallel i}^{(0)}
$$

Consider intensity of turbulent flows, $\,\, \langle u_\perp^2\rangle$ and $\,\, \langle u_\parallel^2\rangle$ under effect of the global rotation:

$$
(1 + 4\tau_c^2 \Omega^2) \langle u_\perp^2 \rangle = \langle u_\perp^{(0)2} \rangle; \langle u_\parallel^2 \rangle = \langle u_\parallel^{(0)2} \rangle
$$

Here we again employ identity $\varepsilon_{\rm ijn} u_{\perp j} \Omega_n \varepsilon_{\rm ipm} u_{\perp p} \Omega_m$ $=$ $(\delta_{\rm jp} \delta_{\rm nm} - \delta_{\rm jm} \delta_{\rm np}) u_{\perp j} \Omega_n u_{\perp p} \Omega_m$

With increase of the rotation rate the turbulence become highly anisotropic

- The mixing in direction which is perpendicular to rotation axis become less turbulent. The turbulent diffusivity and viscosity become anisotropic.
- The heat flux is anisotropic, the polar regions are heated up
- The α effect is anisotropic and it is suppressed along the rotation axis (Kitchatinov & Ruediger 1993)

α^2 dynamo is not efficient for the fast rotators 22/25

The Coriolis force suppress turbulent motion across the axis of rotation (Busse columns), disabling α^2 generation of the axisymmetric toroidal field

How to generate toroidal magnetic field in absence of differetial rotation?

Fold and Twist

 $\mathbf{\mathcal{E}}^{\mathcal{Q}}$ (u x δ b) (B) $b)$

Cross-helicity effect may works near upper boundary of convection zone. For the Sun may be less important because spots are small.

Example of cross-helicity dynamo model 24/25

Summary 25/25

- The dynamo is a an instability of the large-scale magnetic field.
- The astrophysical objects demonstrate numerous dynamo scenarios
	- $-$ Cyclic dynamos are typical for the partially convective stars. Here the dynamo is due to the large-scale flow (differential rotation generate *B'* $\big)$ and turbulent generation, e.g., α effect, generate B^p , $|B^\varphi| \gg |B^p|$. *j*.
	- $-$ Steady dynamos are typical for the fully convective stars and planet as well.
Here, $|B^{\varphi}| \sim |B^p|$ these objects are examples of turbulent dynamos: α^2 , , or $\alpha^2 \Gamma$ $\binom{2}{1}$
- The global rotation results to the anisotropy of the turbulent effects
	- $-$ anisotropy of α effect, the axisymmetric α^2 dynamo is suppressed,
	- $-$ anisotropy of turbulent diffusion and the heat flux